Sizing and Partitioning Strategies for Burst-Buffers to Reduce Contention

Guillaume Aupy, Olivier Beaumont, Lionel Evraud-Dubois



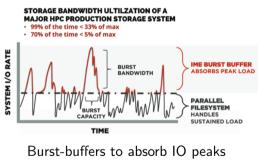


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Motivation

IO congestion in HPC systems:

- HPC applications are generating lots of data for PFS.
- Idea is to use a buffer when the I/O bandwidth is fully occupied
- The buffer can be emptied at a later time.



Source: DDN ad material.

Application Context

Main transfer source in large HPC applications: checkpoints (\Rightarrow predictable)

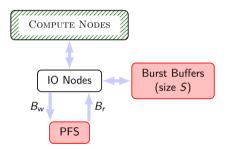
Possible usages for Burst-buffers:

- accelerate one application by caching writes
- hide contention coming from several applications writing at the same time

And with BigData applications coming:

- prefetch input data
- cache for temporary data

Platform model



Applications run on Compute Nodes

Placement already done

Two buffer management policies:

- ► STATIC: size S_k alloted to application A_k for its lifetime
- ► DYNAMIC: size devoted to A_k can change over time

Application model

Set of applications A_k running independently on the platform:

- with release date r_k , read and write bandwidth b_k^r and b_k^w
- consisting of n_k phases (without overlap):

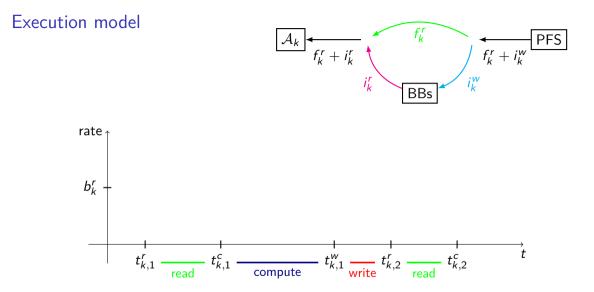
 $C_k^{\min} = r_k + \sum_{i=1}^{n_k} \left(\frac{R_i^k}{b_{\iota}^k} + I_i^k + \frac{W_i^k}{b_{\iota}^w} \right)$

- Read a volume of R_i^k input data starts at $t_{i,k}^r$
- Compute for I_i^k amount of time starts at $t_{i,k}^c$
- Write a volume of W_i^k output data starts at $t_{i,k}^w$
- ▶ No overlap: data available from the start, but two phases do not fit in memory

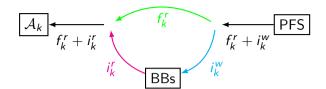
Earliest possible completion time:

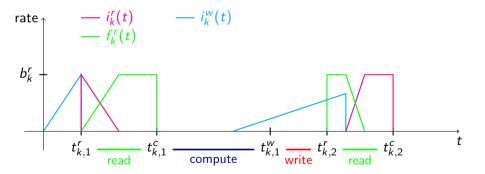
Stretch of \mathcal{A}_k :

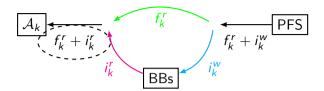
$$s(\mathcal{A}_k) = rac{C_k}{C_k^{\mathsf{min}}}$$

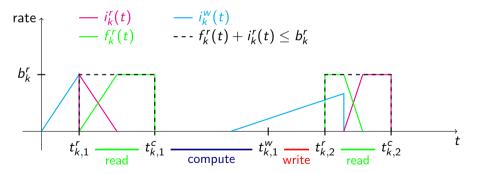


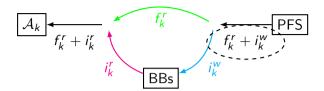
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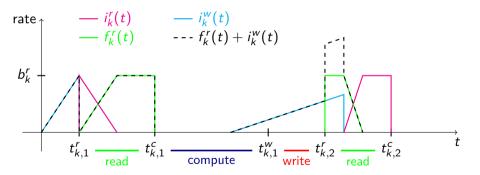


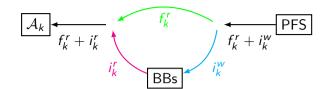


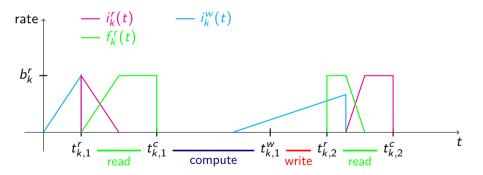




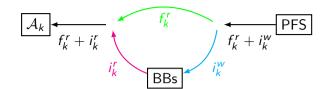


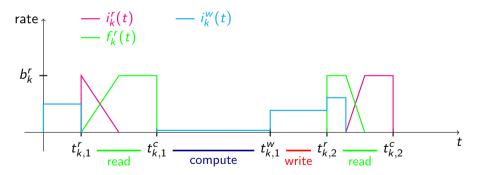




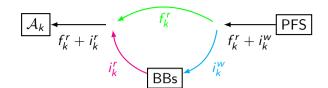


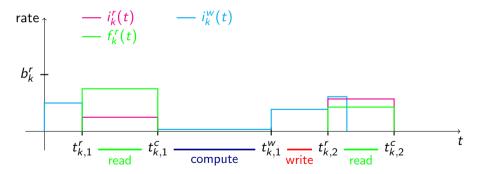
Dominant schedules: all transfer rates constant between time events





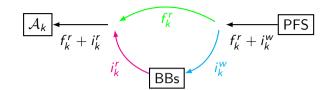
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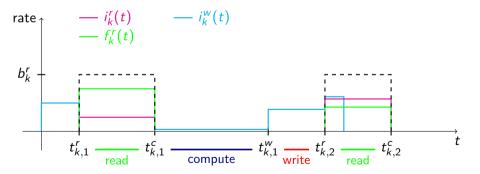




Dominant schedules: all transfer rates constant between time events

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Dominant schedules: all transfer rates *constant* between time events Completely determined by the *amount* of data transferred at each event

Problem formulations – both Static and Dynamic

STATIC-BUFFER-SIZE(ρ) and DYNAMIC-BUFFER-SIZE(ρ)

Given *n* applications (A_k) , and a stretch limit ρ , minimize the total buffer size *S* necessary to achieve stretch ρ .

STATIC-STRETCH(S) and DYNAMIC-STRETCH(S)

Given *n* applications (A_k) , and a buffer size *S*, minimize the maximum stretch over all applications

Results

- ► X-STRETCH(0) is NP-complete
- X-BUFFER-SIZE(ρ) is NP-complete for $1 < \rho \leq 2$
- ▶ STATIC-STRETCH(S) is NP-complete for all S

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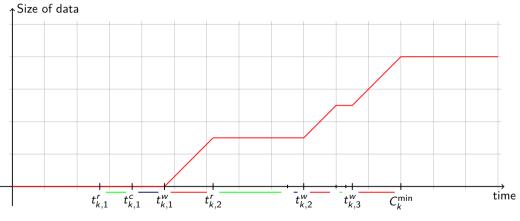
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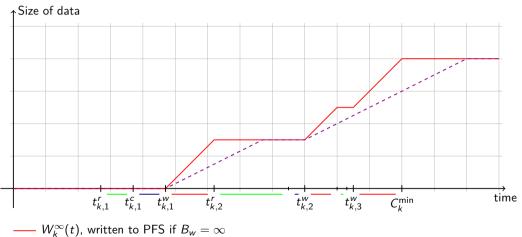
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- ▶ STATIC-STRETCH(S) is NP-complete for all S
- X-Buffer-Size(1) can be solved in polynomial time

Aiming for stretch 1 ($C_k = C_k^{\min}$) fixes the values of $t_{i,k}^*$



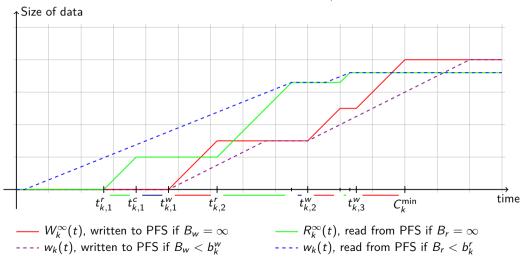
— $W_k^\infty(t)$, written to PFS if $B_w=\infty$

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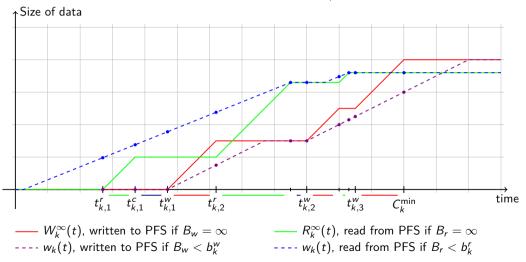


---- $w_k(t)$, written to PFS if $B_w < b_k^w$

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Linear Programming Formulation

Consider all events $\{e_l\} = \{t_{k,i}^*\}$: variables w_k^l and r_k^l , variable S for buffer size

Minimize S subject to:

$$\begin{array}{ll} \forall l, & \underbrace{W_k^\infty(e_l) - w_k^l}_{\text{output data}} + \underbrace{r_k^l - R_k^\infty(e_l)}_{\text{input data}} \leq S & \text{Data stored in buffer} \\ \\ \forall l, & w_k^l \leq w_k^{l+1} & \text{Amount of data is non-decreasing} \\ \forall l, & w_k^l \leq W_k^\infty(e_l) & \text{Can not write more than app. sends} \\ \forall l, & w_k^{l+1} - w_k^l \leq B_w(e_{l+1} - e_l) & \text{Can not write faster than PFS accepts} \\ \\ \forall l, & r_k^l \leq r_k^{l+1} & \text{Amount of data is non-decreasing} \\ \forall l, & r_k^l \leq R_k^\infty(e_l) & \text{Must read at least what app. needs} \\ \\ \forall l, & r_k^{l+1} - r_k^l \leq B_r(e_{l+1} - e_l) & \text{Can not read faster than PFS provides} \end{array}$$

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For several applications

Compute all events $\{e_l\} = \{t_{k,i}^*\}$ for all applications \mathcal{A}_k , in increasing order Variables: w_k^l and r_k^l , S_k^l (buffer size of \mathcal{A}_k at event e_l)

.

Minimize S subject to:

$$\begin{array}{ll} \forall l, & \sum_{k} S_{l}^{k} \leq S & \text{Total buffer size} \\ \forall l, k & W_{k}^{\infty}(e_{l}) - w_{k}^{l} + r_{k}^{l} - R_{k}^{\infty}(e_{l}) \leq S_{k}^{l} & \text{Data stored in buffer} \\ \forall k, l \in \mathcal{I}_{k} & S_{k}^{l} = S_{k} & \text{STATIC constraint} \\ \forall l, k & w_{k}^{l} \leq w_{k}^{l+1} & \text{Amount of data is non-decreasing} \\ \forall l, k & w_{k}^{l} \leq W_{k}^{\infty}(e_{l}) & \text{Can not write more than app. sends} \\ \forall l, & \sum_{k} w_{k}^{l+1} - w_{k}^{l} \leq B_{w}(e_{l+1} - e_{l}) & \text{Can not write faster than PFS accepts} \end{array}$$

[Read constraints]

Settings: applications from LANL Computing Center

EAP	LAP	Silverton	VPIC	
65	21	8	6	1
16	4	32	30	
3,200	2,000	44,800	3,750	'
16	4	32	30	
	65 16 3,200	65 21 16 4 3,200 2,000	65218164323,2002,00044,800	65218616432303,2002,00044,8003,750

Platform characteristics: 96,000 cores B = 160 GB/s b = 20 MB/s per core Period $P = \sqrt{2C \frac{\mu}{\# \text{nodes}}}$ 5 years $\leq \mu \leq 50$ years

Generating instances

- Fix load ρ to 20, 50 or 80%
- Pick 30 applications according to Frequency
- Scheduling them FIFO yields release times
- Compute maximum average bandwidth requirement
- \blacktriangleright Scale checkpoint size to achieve max. load ρ

Settings

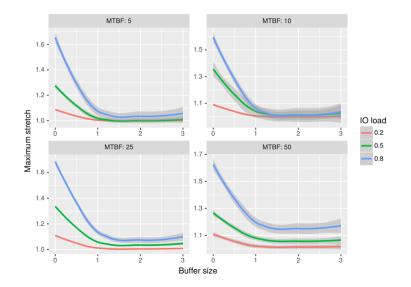
Greedy strategy

- A_k is *active* if it is in a write-phase or has data in its buffer
- Bandwidth to the PFS is equally shared between all active applications
- \mathcal{A}_k sends data at maximum rate b_k^w if its buffer has available space
- Otherwise, A_k is limited to the available bandwidth to PFS

Methodology

- ▶ For each instance, compute S^{OPT} and S_k^{OPT} with STATIC-BUFFER-SIZE(1)
- ▶ S varies between 0 and $3S^{OPT}$, scale S_k accordingly
- Apply Greedy strategy, compute maximum stretch

Results



Overhead of STATIC vs $\operatorname{DYNAMIC}$

Compare the optimal solutions with and without the $\ensuremath{\mathrm{STATIC}}$ constraint

$\textbf{Load} \setminus \textbf{MTBF}$	5 y	10 y	25 у	50 y
20%	1.32	1.31	1.42	1.67
50%	1.33	1.28	1.26	1.47
80%	1.23	1.26	1.25	1.35

Static constraint yields roughly 30% overhead

Conclusions

Remarks about model

- Previous paper [IPDPS'18]: random application behavior, Markov Chain modeling
- ► Here: all phases of applications are known, Linear Programming optimal solution

Perspectives

- > Within this model: efficient strategies for small buffer size
- > Extend the model: data reuse, temporary checkpoint data